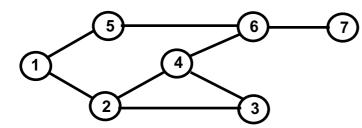
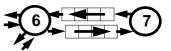
8. Messages in Distributed Systems Distributed processes: Broadcast in a net of processors

Net: bi-directional graph, connected, irregular structure; node: a process

edge: a pair of links (channels) which connect two nodes in both directions

A node knows only its direct neighbours and the links to and from each neighbour:





Broadcast:

A message is sent from an initiator node such that it reaches every node in the net. Finally all channels have to be empty.

Problems:

- graph may have cycles
- nodes do not know the graph beyond their neighbours

Lecture Parallel Programming WS 2014/2015 / Slide 71

Objectives:

Understand the task

In the lecture:

Explain

- the task,
- why the limited knowledge is a problem,
- why it is non-trivial to empty the channels.

Broadcast method

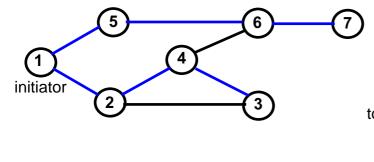
Method (for all nodes but the initiator node):

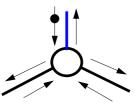
- 1. The node waits for a message on its incoming links.
- 2. After having **received the first message** it sends a **copy to all of its n neighbours** including to the sender of the first message
- 3. The node then receives n-1 redundant messages from the remaining neighbours

All nodes are finally reached because of (2).

All channels are finally empty because of (3).

The connection to the sender of the first message is considered to be an edge of a **spanning tree** of the graph. That information may be used to simplify subsequent broadcasts.





total number of messages: 2*|edges|

Lecture Parallel Programming WS 2014/2015 / Slide 72

Objectives:

© 2011 bei Prof. Dr. Uwe Kastens

Understand the broadcast method

In the lecture:

Explain

- the method,
- that a node knows only one of its spanning tree edges.

Questions:

• Explain why a copy is send to the sender of the first message, too.

PPJ-72

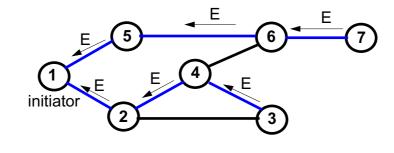
Probe and echo in a net

Task: An initiator requests combined information from all nodes in the graph (probe). The information is combined on its way through the net (echo);

e. g. sum of certain values local to each node, topology of the graph, some global state.

Method (roughly):

- distribute the probes like a broadcast,
- let the first reception determine a spanning tree,
- return the echoes on the spanning tree edges.



Lecture Parallel Programming WS 2014/2015 / Slide 73

Objectives:

Understand the probe/echo task

In the lecture:

Explain

- the task and the method,
- that the nodes do not know their outgoing spanning tree edges.

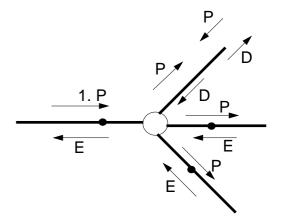
Questions:

• How can a node distinguish outgoing spanning tree edges from other edges?

Probe and echo: detailed operations

Operations of each node (except the initiator):

- The node has **n neighbours** with an **incoming and outgoing link to each** of them.
- After having received the first probe from neighbour s, send a probe to all neighbours except to s, i. e. n - 1 probes.
- Each further **incoming probe** is replied with a **dummy** message.
- Wait until **n** 1 dummies and echoes have arrived.
- Then combine the echoes and send it to s.



PPJ-74

2 messages are sent on each spanning tree edge.

4 messages are sent on each other edge.

Lecture Parallel Programming WS 2014/2015 / Slide 74

Objectives:

© 2011 bei Prof. Dr. Uwe Kastens

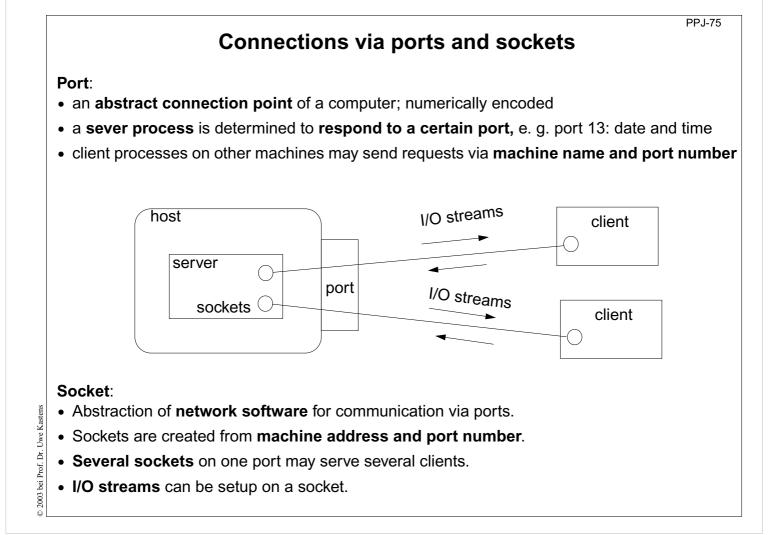
Understand the operations

In the lecture:

- Process does not know which of the outgoing edges belong to the spanning tree.
- Further probes arrive on non-spanning-tree edges.
- They are replied by dummies.

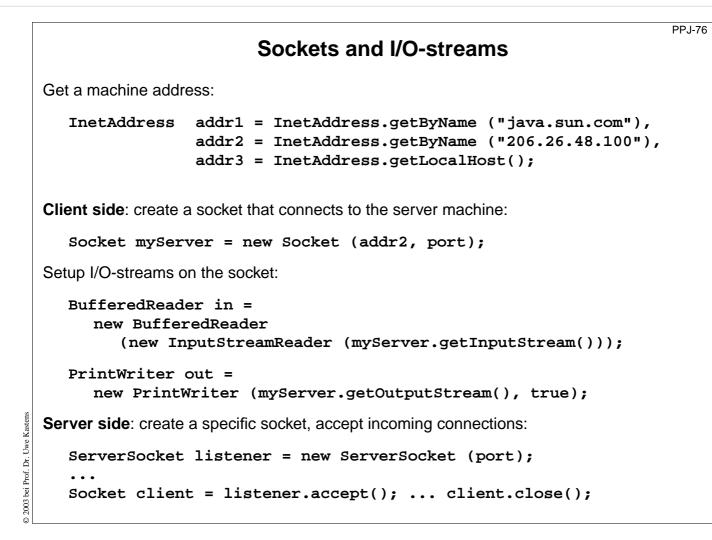
Questions:

• How can the method be simplified if probe and echo is to be executed several times?



Objectives: Understand ports and sockets

In the lecture: Explain it.

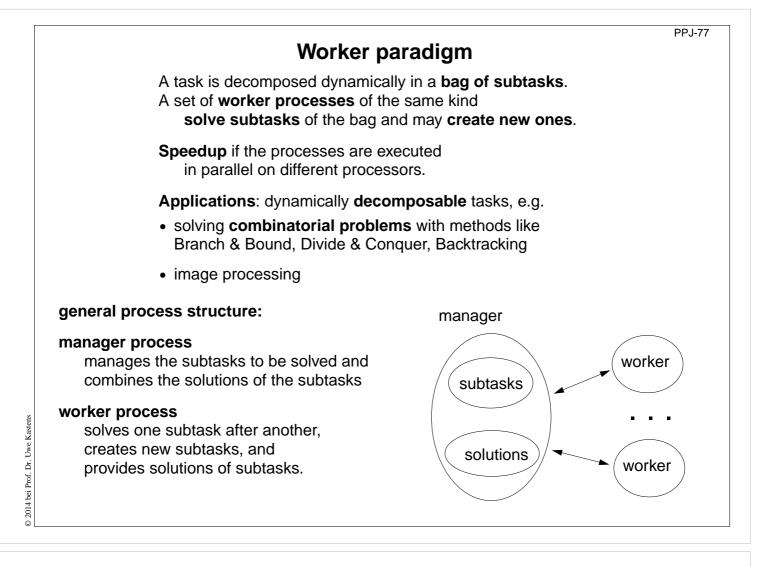


Objectives:

Using sockets

In the lecture:

- Explain how to
- get machine addresses,
- create sockets and streams,
- accept clients and create processes for them.



Objectives:

A paradigma for a class of algorithms

In the lecture:

- Remind the algorithmic methods, and
- their parallelization.

Questions:

• Give examples for combinatorical problems.

Branch and Bound

tree structured solution space is searched for a best solution

General scheme of operations:

- partial solution S is extended to S_1 , S_2 , ... (e. g. add an edge to a path)
- is a partial solution valid? (e. g. is the added node reached the first time?)
- is S a complete solution? (e. g. are all nodes reached)
- MinCost (S) = C: each solution that can be created from S has at least cost C (e. g. sum of the costs of the edges of S)
- Bound: costs of the best solution so far.

Data structures: a queue sorted according to MinCost; a bound variable

sequential algorithm:

iterate until the queue is empty:

- remove the first element and extend it
- check the thus created new elements
 - a new solution and a better bound may be found
 - update the queue

Lecture Parallel Programming WS 2014/2015 / Slide 78

Objectives:

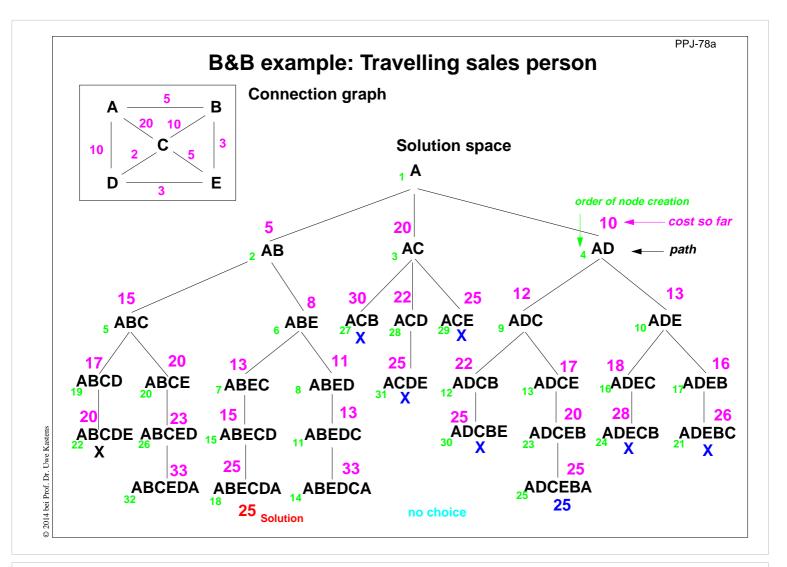
Remember the B&B method

In the lecture:

Explain the general scheme using Traveling Salesperson as an example

Questions:

• Explain the general scheme using the backpack problem as an example.

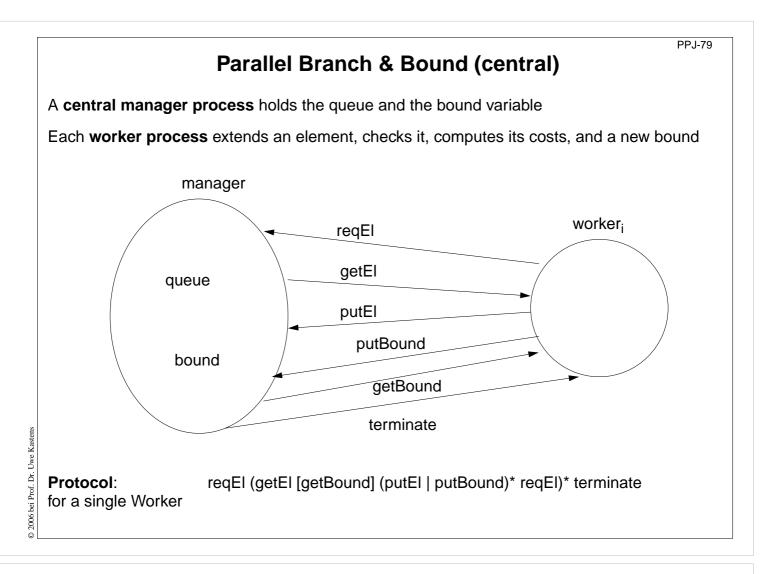


Objectives:

Reminder for TSP computation

In the lecture:

The Branch-and-Bound method is explained. **<u>Get the animated slides.</u>**



Objectives:

Understand the central organization

In the lecture:

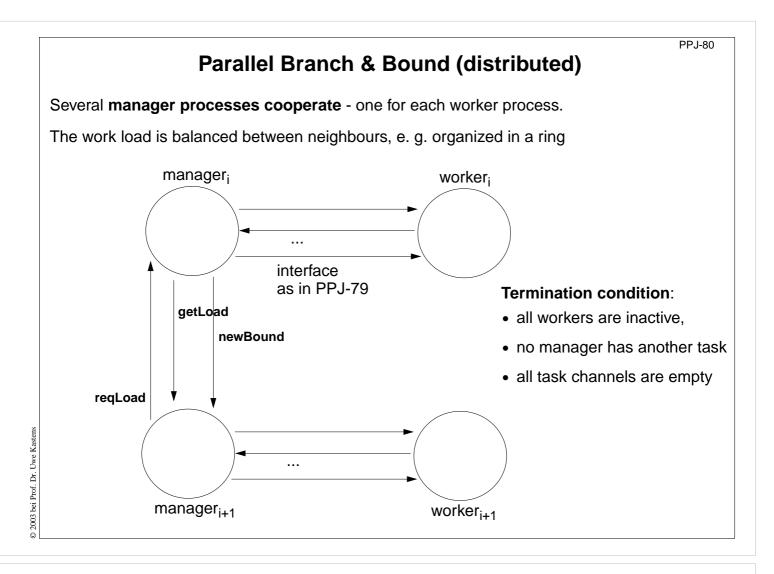
Explain

- the interface,
- the protocol.

Derive them from the general scheme.

Questions:

• Describe how the execution begins and how it terminates.



Objectives:

Understand the distributed configuration

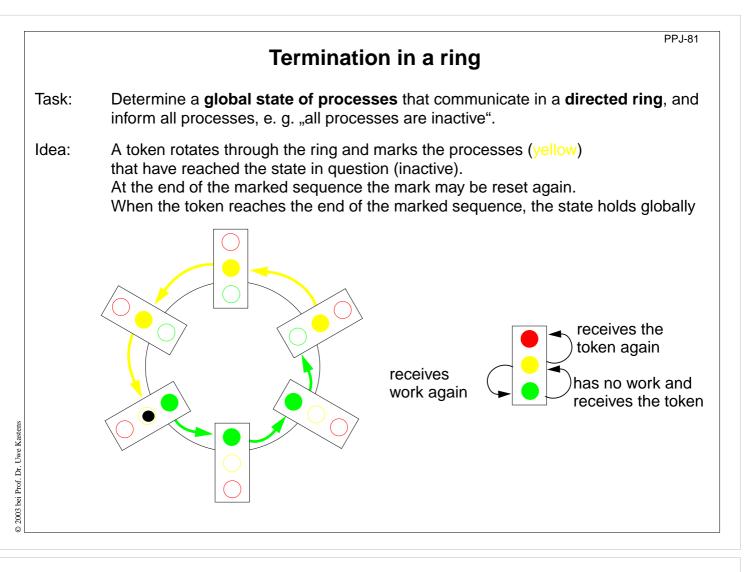
In the lecture:

Explain

- the interface between manager processes,
- the load balancing task,
- the problem of termination,
- the advantages compared to the central configuration.

Questions:

• Compare the central and the distributed configuration.



Objectives:

Understand a technique for distributed termination

In the lecture:

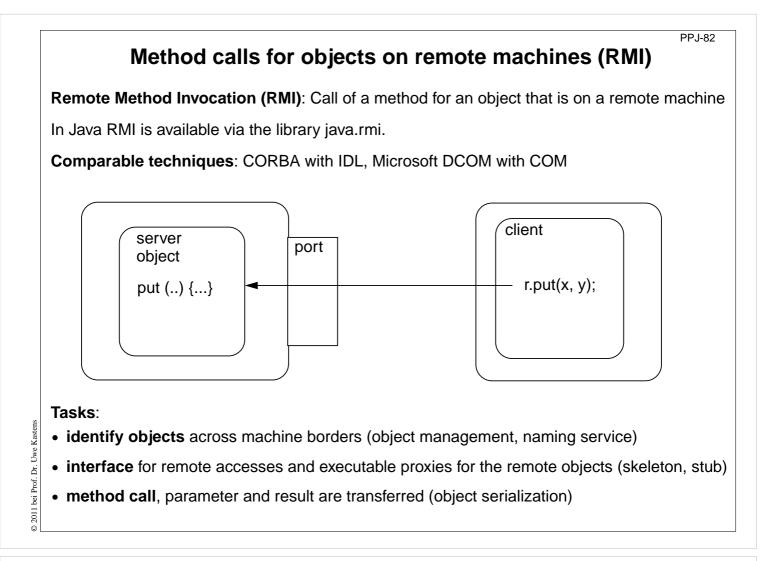
Explain the

- problem, and
- the solution technique,
- use animated slides.

Get the animated slides.

Questions:

- In which situations is the token passed forward?
- How is guaranteed that all channels are empty when all processes are terminated?



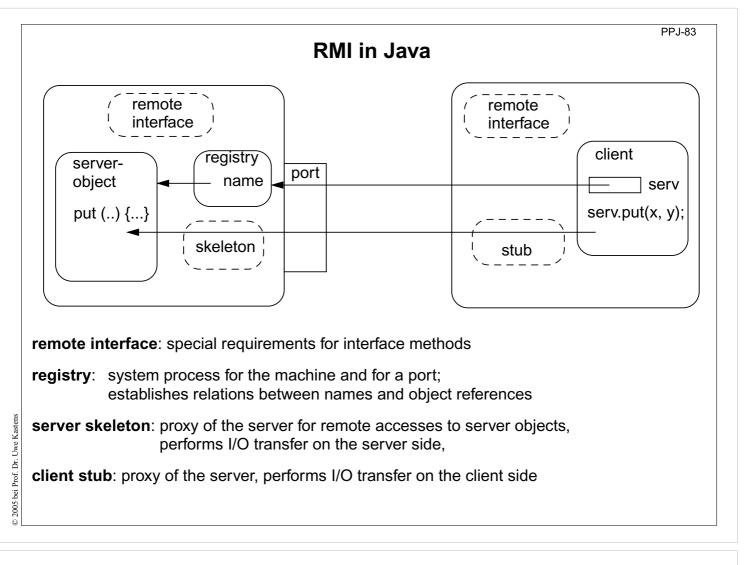
Objectives:

Understand the RMI task

In the lecture:

Explain

- identification of object references,
- representation of objects on $\mathrm{I/O}$ streams,
- transfer of objects.



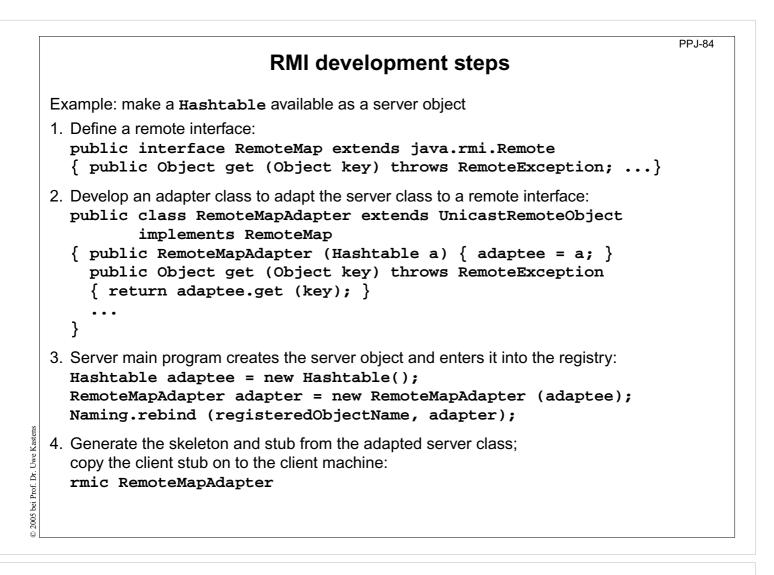
Objectives:

Overview over the components

In the lecture:

Explain

- Registry is a stand-alone process.
- Registry can map many objects.
- Skeleton and Stub are generated.



Objectives: A work plan

In the lecture: Explain the steps

RMI development steps (continued)

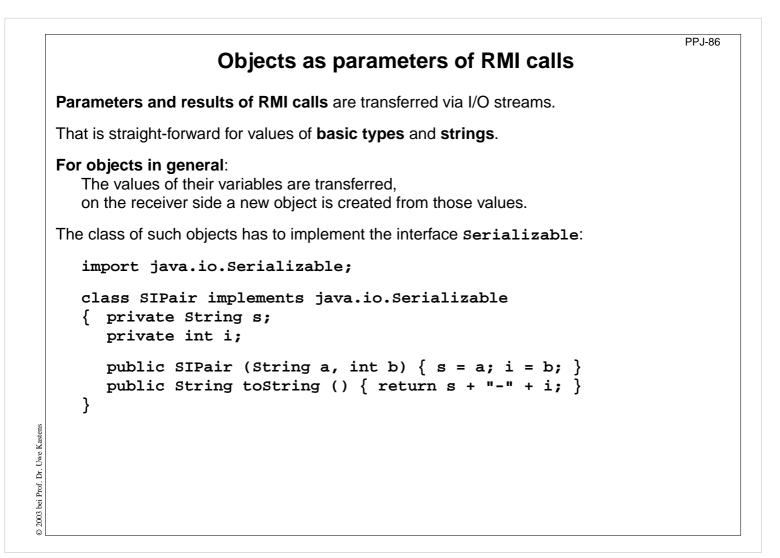
5. Client identifies the server object on a target machine and calls methods: Registry remoteRegistry = LocateRegistry.getRegistry (hostName); RemoteMap serv = (RemoteMap) remoteRegistry.lookup (remObjectName); v = serv.get (key);

- Start a registry on the server machine: rmiregistry [port] & Default Port is 1099
- 7. Start some servers on the server machine.
- 8. Start some clients on client machines.

Lecture Parallel Programming WS 2014/2015 / Slide 85

Objectives: Work plan (continued)

In the lecture: Explain the steps.



Objectives: Transfer of objects

In the lecture: Explain it